Spatial chaos of traveling waves has a given velocity

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We study the complexity of stable waves in unidirectional bistable coupled map lattices as a test tube to spatial chaos of traveling patterns in open flows. Numerical calculations reveal that, grouping patterns into sets according to their velocity, at most one set of waves has positive topological entropy for fixed parameters. By using symbolic dynamics and shadowing, we analytically determine velocity-dependent parameter domains of existence of pattern families with positive entropy. These arguments provide a method to exhibit chaotic sets of stable waves with arbitrary velocity in extended systems.

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I. INTRODUCTION

Pattern formation in spatially extended systems can be regarded as the outcome of nonlinear dynamical processes [1]. This approach has proved successful to a vast phenomenology of various systems in hydrodynamics, optics, solidstate physics, etc. The most basic example concerns the spreading of simple coherent structures (e.g., fronts) in systems dominated by homogenization effects such as in reaction-diffusion [2] or in some examples of population dynamics [3]. In other circumstances, when localization effects are predominant, spatial chaos can emerge along with the production of cohorts of stable heterogeneous profiles, as in bistable optical devices [4] or in the Faraday instability of surface waves [5]. A breakthrough in the endeavor to elucidate this phenomenon has been to interpret solutions of stationary equations as the trajectories of a dynamical system where the original space variable plays the role of time. In this framework (which equally applies to continuous and discrete models) spatial chaos amounts to the existence of horseshoes and results from standard geometric constructions [6].

Beside standing patterns, extended systems also often generate a large variety of propagating structures especially when submitted to a global drift (e.g., open flows) [7]. In spite of this ubiquity, estimates on traveling pattern diversity are scarce, in particular as far as the velocity dependence is concerned. Indeed, stable waves with distinct velocities are known to possibly coexist, but the occurrence of two or more chaotic sets of structures with distinct velocities remains unraveled. Appraising this issue from a theoretical viewpoint might have potential experimental applications in various fields, e.g., in fluid systems [7] or in secure communication [8]. In this context, the spatial dynamical system approach can also serve to construct horseshoes of traveling waves (TWs) [9]. In principle, this tool also proves efficient to obtain conditions for chaos of waves with prescribed velocity (stationary solutions are regarded here as TW with vanishing velocity). However, since the velocity needs to be specified, it does not help to investigate the complexity dependence on velocity and parameters.

To gain intuition on these global features of spatial chaos in extended systems, we focus here on a minimal open flow model that can generate TW of arbitrary velocity, namely, a unidirectional bistable coupled map lattice (CML). Spatial chaos is quantified by the entropy of the sets of TW patterns with identical velocity. We numerically compute the entropyvelocity diagram in parameter space. The diagram unexpectedly reveals that spatial chaos occurs for at most a single velocity at once. To support this observation with analytical results, we rigorously infer, by means of symbolic dynamics, velocity-dependent parameter domains where specific TW pattern sets exist with positive entropy. These estimates show excellent agreement with numerical results, and they extend to a larger class of models by structural stability. In a broader perspective, our shadowing arguments provide a method to exhibit chaotic sets of stable waves with arbitrary velocity in extended systems.

II. CML AND ITS SYMBOLIC DYNAMICS

We consider the unidirectional CML [7] on infinite real sequences,

$$x_s^{t+1} = [F_{\epsilon}(x^t)]_s = (1 - \epsilon)f(x_s^t) + \epsilon f(x_{s-1}^t), \quad (1)$$

where $s \in \mathbb{Z}$ are index lattice sites and *t* represents time and the coupling constant ϵ lies in [0,1]. The individual map *f* is piecewise linear, with two distinct branches separated by a jump at x=T (0 < T < 1), i.e., f(x)=ax+(1-a)H(x-T), *H* being the Heaviside function and $0 \le a < 1$. This type of bistable CML is reminiscent of gradient flows modeling advection phenomena in atmospheric circulation systems [10]. The dynamics under iterations of *f* is elementary; any initial point located below the threshold *T* monotonically converges to the fixed point 0. Likewise, any point above *T* is attracted by 1.

The symbolic dynamics in this CML relies on the natural coding that consists in assigning a symbol 0 or 1 to each coordinate, according to its location with respect to *T*, namely, let $\theta_s^t = H(x_s^t - T)$. In that way, symbolic codes can be explicitly inserted in Eq. (1) via $f(x_{s-r}^t) = ax_{s-r}^t + (1-a)\theta_{s-r}^t$ (*r*=0, 1). By iterating backward the resulting expression, one gains a formula for the coordinates of orbits in the attractor (i.e., of those sequences {*x*^t} whose components exist and are

bounded for all $t \in \mathbb{Z}$) that exclusively depends on the code [11]

$$x_{s}^{t} = \sum_{k=1}^{\infty} \sum_{n=0}^{k} \ell_{n,k} \theta_{s-n}^{t-k},$$
(2)

where the coefficients $\ell_{n,k} = (1-a)a^{k-1} {k \choose n} (1-\epsilon)^{k-n} \epsilon^n$ are positive and normalized. Expression (2) is useful for two reasons. First, it establishes a continuous bijection between codes and CML orbits; especially that given a symbolic sequence $\{\theta_s^l\}_{s,t\in\mathbb{Z}}$, there corresponds (if it exists) a single orbit $\{x_s^l\}_{s,t\in\mathbb{Z}}$ in the attractor. This correspondence commutes with F_{ε} and with space translations; hence all topological properties of the attractor express in symbolic codes. Second, Eq. (2) provides a substitute to the study of the attractor. An *admissibility equation* is obtained by requiring that the code computed based on Eq. (2) be indeed identical to the original symbolic sequence, i.e., a symbolic sequence $\{\theta_s^l\}$ codes for a genuine orbit if and only if (iff) the following relation holds:

$$H\left(\sum_{k=1}^{\infty}\sum_{n=0}^{k}\ell_{n,k}\theta_{s-n}^{t-k}-T\right)=\theta_{s}^{t},\quad\forall s,t\in\mathbb{Z}.$$
(3)

III. SPATIAL COMPLEXITY OF TRAVELING WAVES

Due to the advection term in Eq. (1), a characteristic feature of the CML is the prevalence of traveling patterns [7,10]. Accordingly, in the analysis of Eq. (3), we focus on symbolic sequences corresponding to traveling waves, i.e., $\theta_s^t = \theta_{|s-vt|}$, where $\lfloor \cdot \rfloor$ stands for the integer part [12]. This consideration substantially reduces the variety of solutions to study as these spatiotemporal sequences are parametrized by a purely spatial sequence $\{\theta_s\}$, called a *pattern*, and by a velocity v. However, TW seem to capture the essential characteristics of the attractor in our case. Of note, for $\epsilon=0$ any TW sequence with v=0 and arbitrary pattern in $\{0,1\}^{\mathbb{Z}}$ solves Eq. (3) (i.e., the uncoupled system F_0 has full diversity of fixed points) and similarly for $\epsilon=1$, any pattern is admissible with velocity v=1.

Another simplification comes from symmetries in parameter space. Beside the trivial exchange $(T, x_s^t) \leftrightarrow (1-T, 1 - x_s^t)$ (for orbits off discontinuities) which implies reflection invariance with respect to T=1/2, a more subtle symmetry exchanges any TW of velocity v for ε with a TW of velocity 1-v for $1-\epsilon$ (reflection with respect to $\epsilon=1/2$). This property follows from the relation $F_{1-\epsilon} \circ R = \tau \circ R \circ F_{\epsilon}$, where $(Rx)_s = x_{-s}$ and $(\tau x)_s = x_{s-1}$ are the spatial reflection and translation, respectively.

To get insights for arbitrary couplings, we have numerically estimated the TW entropy [13] depending on the velocity (Fig. 1). The figure reveals a surprisingly elaborated structure where the entropy appears to be positive for at most a single velocity when all parameters are fixed, i.e., no overlapping colored points were found. Hence, chaos of stable TW has a given velocity in our system. This property is rather unexpected because some TW with distinct speeds are known to coexist here. The selected velocity increases from 0 to 1 with coupling ϵ as expected from the definition of F_{ϵ}

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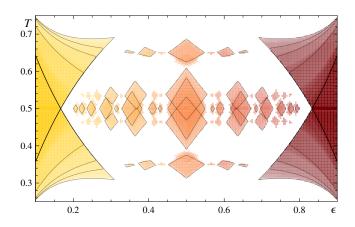


FIG. 1. (Color online) Entropy-velocity diagram of stable TW in (ϵ, T) space for a=0.8. Painted points code for the numerical TW entropy $\frac{\ln P_{19,v}}{19}$ (the period L=19 is chosen large enough for robustness). Gray levels (colors) correspond to velocities v, from 0—left (light gray, yellow) to 1—right (dark gray, brown) and including $\frac{1}{7}, \frac{1}{6}, \frac{1}{5}, \frac{1}{4}, \frac{2}{7}, \frac{1}{3}, \frac{2}{5}, \frac{3}{7}, \frac{1}{2}$ and symmetric values. Intensity is proportional to entropy (maximal values along the axis T=0.5). Curves delimit regions where TW symbolic sequences—with arbitrary pattern in a given chaotic set and given velocity—were analytically proved to solve Eq. (3), see text.

and remains locked on rational values according to structural stability [14]. In particular, a velocity plot vs ϵ for T=1/2 would show a Devil's staircase. Furthermore, the entropy itself remains constant on significant domains and surprisingly, besides reaching a maximum for symmetric maps f, this quantity for 0 < v < 1 may also reach high values far away from T=1/2.

IV. FIXED-POINT ANALYSIS

To put numerical results on an analytic footing, we begin our investigations on Eq. (3) by the spatial chaos of fixed points which materialize in the light gray (yellow) domain of Fig. 1. For a time-independent code $\theta_s^t = \theta_s$, the orbit is obviously a fixed point whose coordinates are given by x_s $= \sum_{n=0}^{\infty} \ell_n \theta_{s-n}$, where

$$\ell_0 = \frac{(1-a)(1-\epsilon)}{1-a+a\epsilon} \quad \text{and} \quad \ell_n = \frac{(1-a)\epsilon(a\epsilon)^{n-1}}{(1-a+a\epsilon)^{n+1}}, \quad n > 0.$$

Equation (3) stipulates that the coordinate x_s at all sites s where $\theta_s = 1$ must exceed the threshold T (for simplicity, we do not consider the case of coordinates lying on T). Likewise, all coordinates for which $\theta_s = 0$ must lie below T. Since all coefficients ℓ_n are positive numbers, among all possible patterns and lattice sites, the smallest coordinate where $\theta_s = 1$ is $x_s = \ell_0$. Using the normalization $\sum_{n=0}^{\infty} \ell_n = 1$ and a similar argument for the sites where $\theta_s = 0$, one concludes that when the inequalities $1 - \ell_0 < T < \ell_0$ hold, all patterns solve Eq. (3) with v = 0. This condition is precisely the one that defines the central leftmost domain of maximal entropy $\ln(2)$ in Fig. 1. In this case, no coordinate can cross the threshold T under F_{ϵ} , independently of the initial point in $[0, 1]^Z$, i.e., there cannot be any other admissible spatiotemporal sequence.

When T is tuned out of the central leftmost domain, large sets of patterns disappear through analogs of saddle-node bifurcations [15] and the entropy decreases [16] as evidenced by changes in color intensity in Fig. 1. The entropy however does not gradually fall off to zero. It remains locked to positive values on plateaus and suffers abrupt changes on short scales. This staircase behavior can be analytically established for $a \leq 3/4$ (and under more general circumstances) as the fixed-point bifurcation values belong to a Cantor set in this case. In addition, lower bounds on the entropy can be obtained by considering the sets, denoted by A_L (L an arbitrary integer), that contain all patterns where any two consecutive 1s are separated by at least L consecutive 0s. Starting from A_0 (which incorporates all patterns) these sets form a nested sequence with decreasing and asymptotically vanishing entropy as L increases.

As for the admissibility of A_L , since there is no upper limitation on the 0-block length, the smallest coordinate for which $\theta_s = 1$ in this set is again $x_s = \ell_0$. On the other hand, a straightforward argument based on positivity and decay of the coefficients ℓ_n shows that the largest coordinate for which $\theta_s = 0$ is $x_s = m_L \equiv \sum_{n=0}^{\infty} \ell_{1+n(L+1)}$. Hence under the condition $m_L < T < \ell_0$ all patterns in A_L are admissible with velocity 0. The graphs of m_L (L=1,2,3) are shown in the leftmost domain in Fig. 1 and indicate that the sets A_L indeed capture the main features of the fixed-point entropy when Tdecreases. Moreover, the fine structure of the fixed-point entropy can be explained by considering more elaborated families with intermediate restrictions on block lengths (results not shown). Finally, the bottom curve delimiting the leftmost domain represents the graph of $m_{\infty} = \ell_1$, below which the entropy turns out to cancel (see below).

V. INTERMEDIATE VELOCITIES

Unlike for extreme velocities, when v is fixed between 0 and 1, no parameter value exists where the TW entropy is maximal. Nonetheless, it is possible to exhibit domains where the pattern entropy is positive by shadowing orbits with fronts and anti-fronts of the same velocity. In a preliminary step, proceeding similarly as for CML with diffusive couplings [11], one shows that a TW front code (defined as $\theta'_s = H(s-vt)$, v rational) solves the admissibility equation iff the parameters satisfy the inequalities $\eta(v-0) < T \le \eta(v)$, where $\eta(v) = \sum_{k=1}^{\infty} \sum_{n=0}^{\lfloor vk \rfloor} \ell_{n,k}$ increases with v. By symmetry, a front coexists with its symmetric antifront under the condition

$$\omega(v) \equiv \max\{\eta(v-0), 1-\eta(v)\} < T < 1-\omega(v).$$

This condition defines, for any rational velocity $v = \frac{p}{q}$ and any $0 \le a < 1$, a (symmetric with respect to T=1/2) rhombuslike domain $S_{p/q}$ in the (ϵ, T) square. Moreover, these domains are pairwise disjoint and contiguous when v changes as indicated in Fig. 1.

To prove spatial chaos of TW, we consider the pattern set B_L of positive entropy where all finite 0-blocks and all finite 1-blocks have length L or larger. Any TW code with pattern in B_L and velocity $\frac{p}{q}$ has the property to locally match, on any space-time window of size L, and modulo a time shift t_0 ,

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either the corresponding front code (i.e., we have $\theta_{s'}^{'}=H[s' - \frac{p}{q}(t'-t_0)]$ for $s-L < s' \le s$ and $t-L < t' \le t$) or the antifront code. According to Eq. (2) and to normalization of the $\ell_{n,k}$, the coordinate x_s^t then turns out to be close to either the front coordinate, i.e.,

$$\left| x_s^t - \phi_{\text{front}} \left(s - \frac{p}{q} (t - t_0) \right) \right| < a^{L-1}, \tag{4}$$

or to the antifront's coordinate. In addition, inside $S_{p/q}$, all front and antifront coordinates are bounded away from the threshold *T* uniformly in space time, say at a distance $\delta > 0$. By choosing *L* large enough so that $a^{L-1} < \delta$ (i.e., $L \ge L_0$), the inequality (4) forces x_s^t and $\phi_{\text{front}}[s - \frac{p}{q}(t-t_0)]$ to be either both above or both below the discontinuity *T* (and similarly when x_s^t is close to the anti-front coordinate), i.e., Eq. (3) holds at arbitrary point (s,t). We conclude that all patterns in B_{L_0} are admissible with $v = \frac{p}{q}$ and a positive lower bound applies for the associated pattern entropy inside $S_{p/q}$.

A similar shadowing argument can be applied to patterns in the sets A_L above to gain further domains with positive entropy. The reference orbit in this case is unique; it is the soliton coded by $\theta_s^t = \delta(s - vt)$, where δ stands for the Dirac distribution. In practice, we have determined soliton existence domains, analytically for the velocity 1/2 and numerically for v=1/3 and 1/4. Their cross sections for a=0.8, called $D_{p/q}$, are represented on Fig. 1 (bottom rhombuslike domains). As before, an excellent agreement is found with the corresponding regions of numerically evidenced positive entropy. Finally, we note that the shadowing argument can be repeated with further orbits to get additional predictions on the entropy. For instance, the numerically computed existence domains for the two-site solitons with v = 1/2, 1/3 and 1/4 are reported in Fig. 1. These are the rhombuslike structures intersecting their respective symmetric domain $S_{p/q}$.

VI. COMPLETING THE DIAGRAM

In addition to domains of positive entropy, we determined regions where the entropy cancels. In particular we proved that, under the condition $0 < T < \min\{\ell_0, \ell_1\}$, (i) any symbol 1 remaining steady long enough at s, eventually forces the neighboring symbol at s+1 to become 1 and on the opposite (ii) the symbols 0 do not propagate (i.e., $\theta_s^t = 1$ implies θ_s^{t+1} =1). In this case, any code asymptotically approaches a sequence composed of front profiles [i.e., $\theta_s^t = H(s - s(t))$] and any TW entropy must vanish. By applying the symmetries $T \mapsto 1 - T$ and $\epsilon \mapsto 1 - \epsilon$, one obtains large domains of low spatial complexity in the parameter space that share common boundaries with positive entropy domains as shown on Fig. 2. Of note, in the limit a=0 the CML becomes a cellular automaton. No TW with intermediate velocity exists in this case and there are four possible automaton rules according to the location of (ϵ, T) in the unit square.

VII. CONCLUDING REMARKS

Our analysis indicates that once the parameters are fixed in this system, various sets of TW coexist with distinct ve-

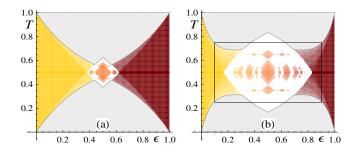


FIG. 2. (Color online) Entropy-velocity diagram in the (ϵ, T) -square and complementary domains where the entropy is analytically shown to cancel (outer light gray regions). (a) a=0.4 and (b) a=0.8; the rectangle delimits the region displayed in Fig. 1.

locities [17], but only a single ensemble can be chaotic. Numerical evidence has been supported by analytic arguments based on families of symbolic sequences. In a larger perspective, structural stability [14] implies that all chaotic sets exhibited here can be continued into suitable alterations of the piecewise affine model. Thus the existence of chaos of TW with arbitrary velocity generalizes to a larger class of bistable CML and beyond to lattice systems with more general type of coupling (i.e., not fully asymmetric). Furthermore, based on uniqueness of the front velocity in bistable extended systems, we conjecture that the property of an at most one chaotic traveling patterns set holds in a broad context. Testing this property in further models provides a rewarding challenge for future studies.

Independently, our analytic methods proffer an alternative approach to the horseshoe construction, based on shadowing arguments. Indeed, the presence of a stable soliton (or the coexistence of stable fronts and antifronts of the same velocity) guarantees the existence of ensemble of traveling patterns with positive entropy. As it does not require the explicit expression of localized solutions, this criterion is applicable to arbitrary spatially extended systems.

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- [13] For numerical purposes, the TW entropy is defined here as the exponential growth rate of the number $P_{L,v}$ of *L*-periodic patterns with a given velocity v, i.e., $\limsup_{L\to\infty} \frac{\ln P_{Lv}}{L}$. This quantity is related to the standard topological entropy based on the number of admissible words, see, e.g., R. Badii and A. Politi, *Complexity: Hierarchical Structures and Scaling in Physics* (Cambridge University Press, New York, 1997).
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- [16] For any $T < 1 \ell_0 = \sum_{n=1}^{\infty} \ell_n$, we have $T \le \sum_{n=1}^{L} \ell_n$ for *L* large enough. Thus, every fixed-point pattern containing a (finite) 1-block of length *L* or larger cannot be admissible and the fixed-point entropy must be smaller than ln(2).
- [17] For instance fronts with velocity $v \neq 1/2$ coexist together with a chaotic set of waves with velocity 1/2 in the central bottom domain $D_{1/2}$ of Fig. 1.